

Reference Specifications

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 Incremental Optical Encoder (Hollow shaft- Blind hole) Introduction: K22 is a micro-compact hollow shaft optical encoder, highly reliable, commonly used in small equipment and industrial automation with space constraints. 	K22-J		
 1.2 Feature: Encoder external diameter Ø22mm、 thickness 18mm、 Diameter of shaft up to Ø6.5mm; Adopt non-contact photoelectric principle; Multiple electrical interfaces available; Resolution per turn up to 16384PPR. 		Q	
 Application: Bill counting machines, printers, micro motors, small instruments and other automation control fields. 			
1.4 Connection:Radial cable (standard length 500mm)Axial cable (standard length 500mm)	K22-L		
1.5 Protection: IP50		A	
1.6 Weight: about 35g			

2. Model Selection Guide

2.1 Model composition(select parameters)



2.2 Note

①. Resolution selection is recommended below 5000PPR, Z signal is low level active.

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HENGXIANG /// Encoder

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3. Output mode



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4. Electrical Characteristics

Parameter Output type Item		utput type	OC	TTL			
Supply voltage			DC+5V±5%				
Consumption current			100mA Max				
Allowable ripple			≤3%rms				
Top response frequency			100KHz	200KHz			
	Output current	Input	≤30mA	≤±20mA			
		Output	_				
Output capacity	Output voltage	"H"	_	≥2.5V			
		"L"	≤0.4∨	≤0.5V			
	Load voltage		≤DC30V	-			
Rise & Fall time			Less than 2us(cable length: 2m)	≤100ns Less than 1us(Cable length: 2m)			
Mark to space ratio			45% to 55%				
Phase shift between A & B		8 P	90°±10° (frequency in low speed)				
		A OL	90°±20° (frequency in high speed)				
GND			Not connect to encoder				

5. Mechanical Characteristics

Diameter of shaft	Ø4mm; Ø5mm; Ø6mm; Ø6.5mm (Depth 10mm, Stainless steel material)
Starting torque	Less than $5 \times 10^{-4} \text{N} \cdot \text{m}$
Inertia moment	Less than 1×10 ⁶ kg·m²
Shaft load	Radial 2N; Axial 2N
Slew speed	≤5000 rpm
Shell	Aluminium alloy
Weight	about 35g

6. Environmental Specifications

Environmental temperature	Operating:-20~+80°C; Storage:-25~+85°C		
Environmental humidity	Operating and storage: 35~85%RH(noncondensing)		
Vibration(Endurance)	Amplitude 0.75mm,5~50Hz,2h for X,Y,Z direction individually		
Shock(Endurance)	49m/s ² 11ms three times for X,Y,Z direction individually		
Protection	IP50		

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7. Wiring table

7.1 OC (Wiring table)

	Supply	voltage		Incremental signal		
Wire color	Red	Black	White	Green	Yellow	
Function	Up	0V	A	В	Z	

7.2 TTL (Wiring table)

	Suppl	y voltage	Incremental signal					
Wire color	Red	Black	White	White/BK	Green	Green/BK	Yellow	Yellow/BK
Function	Up	0V	A+	A-	B+	В-	Z+	Z-
Twisted-paired cable								

Up=Supply voltage.

Shield wire is not connected to the internal circuit of encoder.





Unit: mm



= Shaft rotation direction of incremental signal output
 R.1 = Radial cable (standard length 500mm)
 A.1 = Axial cable (standard length 500mm)
 22T24 = Mounting spring plate model

About vibration

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Vibration act on encoder always cause wrong pulse, so we should pay attention to working place. More pulse per revolution, narrower groovy spacing of grating, more effect to encoder by vibration, when rev is low or stop, vibration act on shaft or main body would cause grating vibrating, so encoder might make wrong pulse.



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